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Biscayne Bay, FL (S200) Bathymetric Digital Elevation Model(30 meter resolution) Derived From Source Hydrographic Survey Soundings Collected by NOAA

Identification Information

Title: Biscayne Bay, FL (S200) Bathymetric Digital Elevation Model(30 meter resolution) Derived From Source Hydrographic Survey Soundings Collected by NOAA

Originator: Department of Commerce (DOC), National Oceanic and Atmospheric Administration (NOAA), National Ocean Service (NOS), Special Projects (SP)

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Abstract: Bathymetry for Biscayne Bay was derived from twelve surveys containing 149,227 soundings. The overlap from three older, less accurate surveys was omitted before tinning the data. The twelve surveys used dated from 1930 to 1993. Approximately 60 percent of the surveys were from 1934. Surveys from 1980 to 1993 cover the eastern portion of the bay. The total range of sounding data was 0.6 meters to -10.4 meters at mean low water. Mean high water values between 0.1 and 0.6 meters were assigned to the shoreline. Fourteen points were found that were not consistent with the surrounding data. These were removed prior to tinning. DEM grid values outside the shoreline (on land) were assigned null values (-32676). Biscayne Bay has fifteen 7.5 minute DEMs and a single one degree DEM. The 1 degree DEMs were generated from the higher resolution 7.5 minute DEMs which covered the estuary. A Digital Elevation Model (DEM) contains a series of elevations ordered from south to north with the order of the columns from west to east. The DEM is formatted as one ASCII header record (A-record), followed by a series of profile records (B-records) each of which include a short B-record header followed by a series of ASCII integer elevations (typically in units of 1 centimeter) per each profile. The last physical record of the DEM is an accuracy record (C-record). The 7.5-minute DEM (30- by 30-m data spacing) is cast on the Universal Transverse Mercator (UTM) projection. It provides coverage in 7.5- by 7.5-minute blocks. Each product provides the same coverage as a standard USGS 7.5-minute quadrangle but the DEM contains over edge data. Coverage is available for many estuaries of the contiguous United States but is not complete.

Purpose: Bathymetric DEM's can be used as layers in Geographic Information Systems (GIS) for earth science analysis. DEM's can also serve as tools for volumetric analysis, for site location of structures, or for drainage basin delineation. The source soundings are collected by the NOS Office of Coast Survey (OCS).

Progress: Completed

Frequency: Irregular

Time Period of Content

Date Range

Begin Date: 1930

End Date: 1993

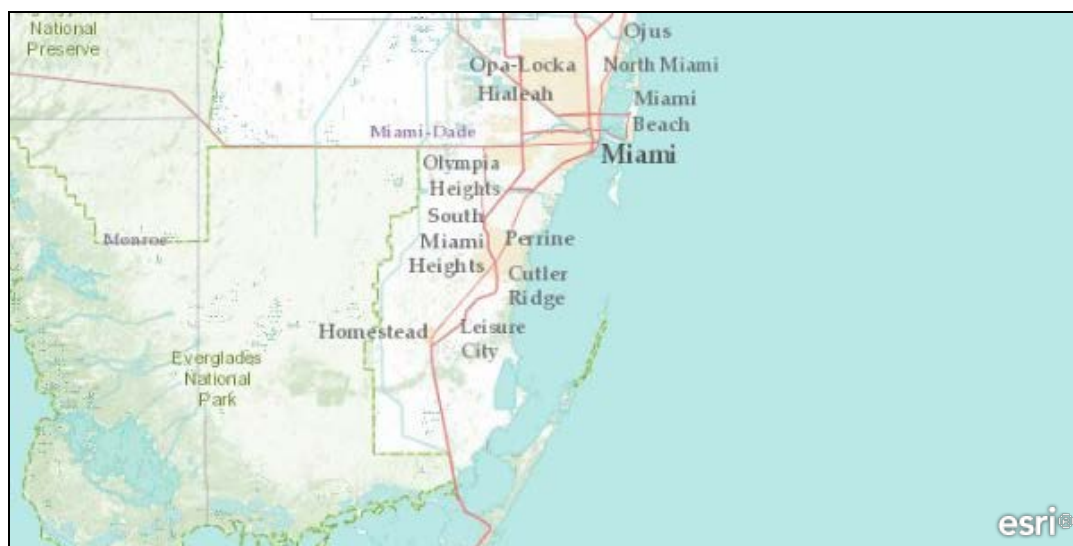
Currentness: ground condition

West Bounding Longitude: -80.434538

East Bounding Longitude: -80.120829

North Bounding Latitude: 25.929548

South Bounding Latitude: 25.177281



Point of Contact

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Constraints

Access: none

Use: Not to be used for Navigation. Acknowledgment of the National Oceanic and Atmospheric Administration- Nation Ocean Service would be appreciated in products derived from these data. The datum for these bathymetric DEMs is not the same as that used by the US Geological survey (USGS) for land based DEMs which results in a discontinuity if the two datasets are merged together. Moreover, the shoreline for the USGS DEMs is indeterminate and not the same as that used for the Bathymetric DEMs. The data within the bathymetry file is floating point. When using the data within a GIS care must be taken to ensure that the data are being read as floating point and not integer data.

Theme Keywords

Theme Reference: none

Theme DEM, digital elevation model, digital bathymetric model, digital terrain model, bathymetry, altitude, height, depth, Topics: Elevation and Derived Products, hydrographic survey, estuary, estuarine bathymetry, marine navigation

Keywords

Theme Reference: ISO 19115 Topic Category

Theme Keywords: oceans, elevation, ImageryBaseMapsEarthCover

Place Keyword Thesaurus: None

Place Keyword: Biscayne Bay, FL, Florida, United States

Data Quality Information

Logical Consistency The fidelity of the relationships encoded in the data structure of the DEM are automatically verified using a NOAA-Consistency NOS software program upon completion of the data production cycle. The test verifies full compliance to the DEM Report: specification.

Completeness The DEM is visually inspected for completeness on a DEM view and edit system for the purpose of performing a final Report: quality control and if necessary, edit of the DEM. The physical format of each DEM is validated for content completeness and logical consistency during production quality control. Due to the variable orientation of the 7 1/2 minute quadrilateral in relation to the Universal Transverse Mercator (UTM) projection grid, profiles that pass within the bounds of the DEM quadrilateral may be void of elevation grid points and are not represented in the DEM. This condition occurs infrequently and is always the first or last profile of the dataset. DEM's may contain void areas caused by elevations being above Mean High Water or on non-tidal land. Void elevations are assigned the value of -32,767. In addition, suspect elevation areas may exist in the DEM but are not specifically identified. Only available data digitized before 1997 were used in this project. Additional sounding information may exist for areas which have holes in the bathymetric data set, but was not available at the time this project was completed. No additional updates or error corrections are planned for this data set.

Positional Accuracy

Horizontal Positional Accuracy The horizontal accuracy of the DEM is expressed as an estimated root mean square error (RMSE). The estimate of the RMSE is based upon horizontal accuracy tests of the source soundings used to generate the DEM. As a first approximation the locational accuracy of the source soundings are 0.0015 m at source "Smooth Sheet" scale Report: (120 m @ 1:80,000 to 15 m @ 1:10,000). Smooth Sheets are maps generated as a principle product of each (historic) hydrographic survey with fully corrected soundings plotted on them.

Accuracy
Value: 3

Accuracy Explanation: Digital elevation models comply with the National Map Accuracy Standards (NMAS) accuracy requirements.

Vertical Positional Accuracy The vertical RMSE statistic is used to describe the vertical accuracy of a DEM. It encompasses both random and systematic errors introduced during production of the data. The RMSE is encoded in element number 5 of record C of the DEM. This accuracy estimate includes components related to quantization of the source soundings (1.3 Report: to 0.15 m), the systematic editing of the source data (1 percent or 0.10m), un-sampled bathymetric features (estimated at less than 5 percent of depth), time related changes (erosion, deposition, and seismic shifts), and dredging operations (cut and fill). It is estimated that the accuracy of the Bathymetric DEMs is 2 percent of depth or 1 meter for depths greater than 20 meters and 2 percent of depth or 0.20 meters for depths shallower than 20 meters. THESE DEMs SHOULD NOT BE USED FOR NAVIGATION. There are three types of DEM vertical errors: blunder, systematic, and random. These errors are reduced in magnitude by editing but cannot be completely eliminated. Blunders are errors of major proportions and are easily identified and removed during interactive editing. Systematic errors follow some fixed pattern and are introduced by data collection procedures and systems. Systematic error artifacts include vertical unsampled elevation shifts, relative spacing of the source soundings, misinterpretation of terrain surface caused by softness or poor reflectivity and by the resolution of the collected soundings (feet, feet and fractions, fathoms, fathoms and fractions, meters, tenths of meters etc.). Random errors result from unknown or accidental causes. The 1 degree (DSQ) DEMs are generated from 30 m grids on UTM projection. The RMSE difference between these surfaces is an estimate of the vertical accuracy of the DSQ DEMs.

Processing Steps

Step 1 Description: The production procedures, instrumentation, hardware, and software used in the collection of standard National Process Oceanic and Atmospheric Administration (NOAA) Bathymetric Digital Elevation Models (DEM's) vary depending on systems used at the time of the survey. Log sheets were kept at all stages of processing to track file names, dates, hydrographic survey coverage, and soundings or hydrographic surveys that were deleted as part of the quality control process. A short summary of the processing steps for each estuary is available on the individual data pages. In addition, a list of each of the surveys which were included is accessible through the individual data pages. Original hydrographic data from the National Ocean Service and its predecessors was used exclusively as source data. Processing was performed on desktop computers using a variety of commercial

and custom software systems. The two main software systems used were Digital Optimization of Grid Systems (DOGS) version 1.5x software developed by NOAA and MapInfo Professional version 4.5 published by MapInfo augmented by a MapInfo add-on named Vertical Mapper published by Northwood Geosciences. The processing sequence for each estuary started with the generation of a comprehensive source data set from the NOS archives. These source soundings were quality controlled to eliminate outliers and superseded surveys, optimized to reduce the number of data values, augmented with points representing the Mean High Water shoreline, and then gridded. The gridded data sets were converted from the internal proprietary grid format to Digital Elevation Model (DEM) format for public distribution.

Creating Point Sets of Hydrographic Survey Data: Sounding data obtained from Hydrographic Surveys were extracted using DOGS from the GEODAS CD distributed by the National Geophysical Data Center using each estuary's shoreline as a clipping boundary. Large estuaries were broken into several overlapping regions and subsets of points were extracted and processed. Most historic hydrographic surveys are included on the GEODAS CD. For those regions which were missing data (parts of southern Florida and Chesapeake Bays only), soundings were digitized from a hard copy Smooth sheets generated by the Hydrographic Surveys.

Editing and Quality Control of Bathymetry Point Data: The first step of the quality control was to review the data using the DOGS software. The data were first examined for surveys or parts of surveys that are redundant. For many areas there are more surveys than are actually useful. Entire surveys or large portions of surveys were deleted for the following reasons: - Another more recent survey fully covers the same area. - The survey has questionable values which can not be fixed by way of figuring out a mathematical update value for the entire survey, and there are too many bad points to pick out probable "good" values. - Sections of surveys were omitted if they were overlapped by more accurate surveys or by similar yet denser coverage.

The second step was to display the data by depth values and to remove stray points that were obvious outliers from the surrounding data values.

Optimizing the Bathymetry Point Data using DOGS: The data was first triangulated in DOGS in order to optimize the set of points. The computer program DOGS can analyze a large set of bathymetric data and create from it a smaller set of optimized points which describes the bathymetry of a geographic region to within a user defined error. This smaller data set then can be used on its own as a representation of the area's bathymetry, or as input into other computer programs or Geographical Information Systems. There are two calculation options for triangulation in DOGS: relative and absolute. Bathymetry point files were cut into sections for separate processing based on mean depth of 10 meters. A relative height error criteria of 0.01 was used for the triangulation of regions whose depths averaged above 10 meters. An absolute height error criteria of 0.1 meters was used for areas with average depths less than 10 meters. The two resultant files were saved as text files. After combining these files, the vertical error associated with the optimized data set was 1 percent of depth or 0.1 meters, whichever was greater. The optimized DOG file was imported into MapInfo's MapInfo Professional desktop mapping software.

Augmenting the data set with Shoreline Points: The final bathymetry was clipped to NOAA's 1:250,000 Coastal Assessment Framework (CAF) shoreline. A copy of the shoreline file was edited to create a point file from the vector vertices and optimized using DOGS to produce a more workable, smaller file, with little compromise to the shape of the shoreline. Mean High Water tide level was assigned to the shoreline points to give them a height. These Shoreline data points were added to the set of bathymetry points before doing the final triangulation in MapInfo.

Generation of a Gridded Bathymetry Dataset: Linear triangulation of the combined point files were done in MapInfo using the Vertical Mapper 2.0 partner product software. The resultant TIN file was then used to create a continuous grid file with 30 meter resolution on a UTM projection using a NAD27 horizontal datum. A second grid was created from the first by aggregating the 30 meter grid values to 90 meter resolution and exporting the 90m center points. A new TIN was created after reattaching the shoreline pts. The triangle side lengths and coincident point distances were small enough to disallow interpolation outside the 90m distance, so as to emulate a rectangular interpolation and still allow the shoreline to be represented without averaging out the values. The result of the new file is a geographic 3 arc second resolution grid. Both grids were cut to the estuary boundary shoreline. 7.5 minute and 1 degree sections were then created from these grids. The 7.5 minute grids have 30 meter resolution in a UTM projection using the NAD27 datum. The 1 degree grids have a 3 arc second resolution in a geographic projection (Latitude/Longitude) using the NAD27 datum. In their native form, both of these grids are in proprietary formats.

Creating DEM files: The MapInfo grid files were converted to a public domain USGS format DEM files using the NOAA DEM maker software. The formats available for downloading are 30 meter and 3 arc second DEMs in USGS DEM format. DEM's are viewed on interactive editing systems to identify and correct blunder and systematic errors. DEM's are verified for physical format and logical consistency.

Step 1

Process Unknown

Date:

 Entity And Attribute Information

Overview: The digital elevation model is composed of a elevation value linked to a grid cell location representing a gridded form of a bathymetric map overlay. Each grid cell entity contains a 6-character integer value between -32,767 and 32,768. The grid is generated from profiles of data each containing header information (profile identifier, starting point, relative datum for profile values (deepest value within the DEM), number of values, etc) followed by profile values relative to the relative datum for the profile. All non-null values in the profile are positive.

Detail U.S. Department of the Interior, U.S. Geological Survey, 1992, Standards for digital elevation models: Reston, VA, is Citation: available at: <http://rockyweb.cr.usgs.gov/nmpstds/demstds.html>

Spatial Reference Information

Geodetic Model

Horizontal Datum Name: North American Datum Of
1927

Ellipsoid Name: Clarke 1866

Semi-major Axis: 6378206.4

Denominator of Flattening
Ratio: 294.98

Distribution Information

Resource Downloadable Data
Description:

Distribution These data were prepared by an agency of the United States Government. Neither the United States Government Liability: nor any agency thereof, nor any of their employees, make any warranty, expressed or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed in this report, or represents that its use would not infringe privately owned rights. Reference therein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. Any views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof. Although all data have been used by NOAA, no warranty, expressed or implied, is made by NOAA as to the accuracy of the data and/or related materials. The act of distribution shall not constitute any such warranty, and no responsibility is assumed by NOAA in the use of these data or related materials.

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/NOSDataExplorer/rest/document?f=html&id=%7B020DA09D-DEB9-441D-8807-CB1FDBD5CDE5%7D

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